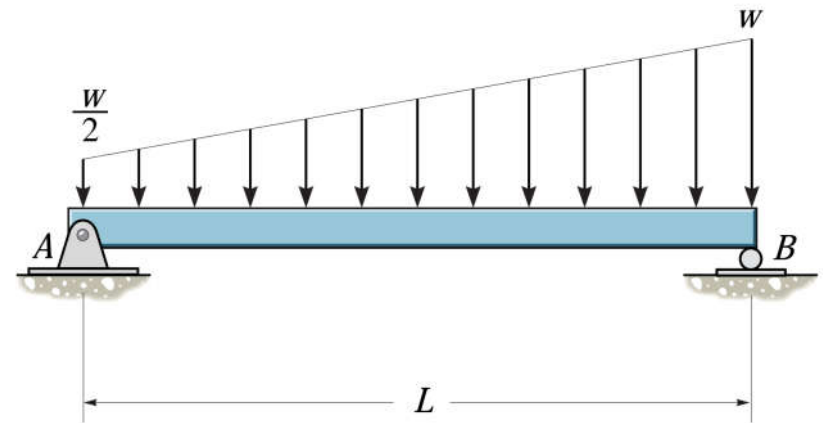
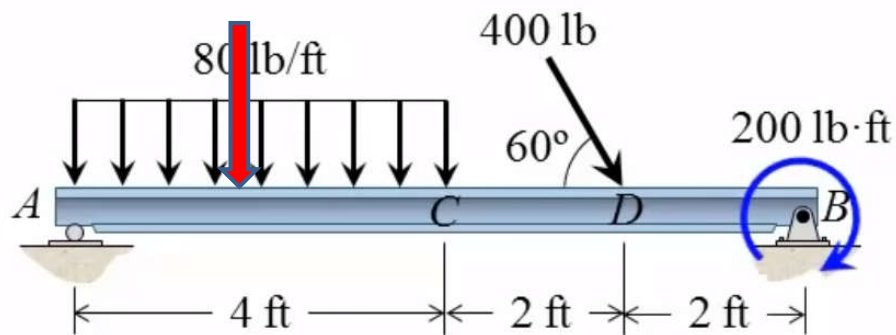


# Geometric properties

## Centre of Gravity

### Objectives:

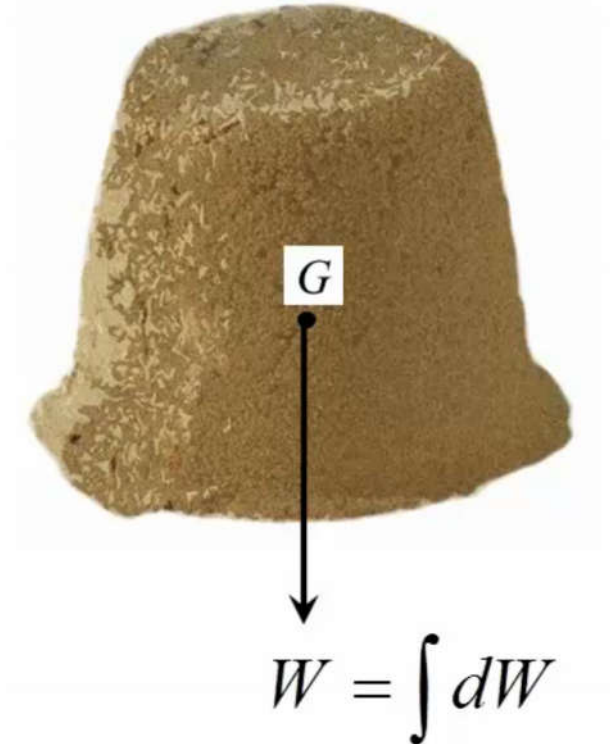
- You will be able how to find the center of gravity of a rigid body



## Engineering Mechanics: Statics

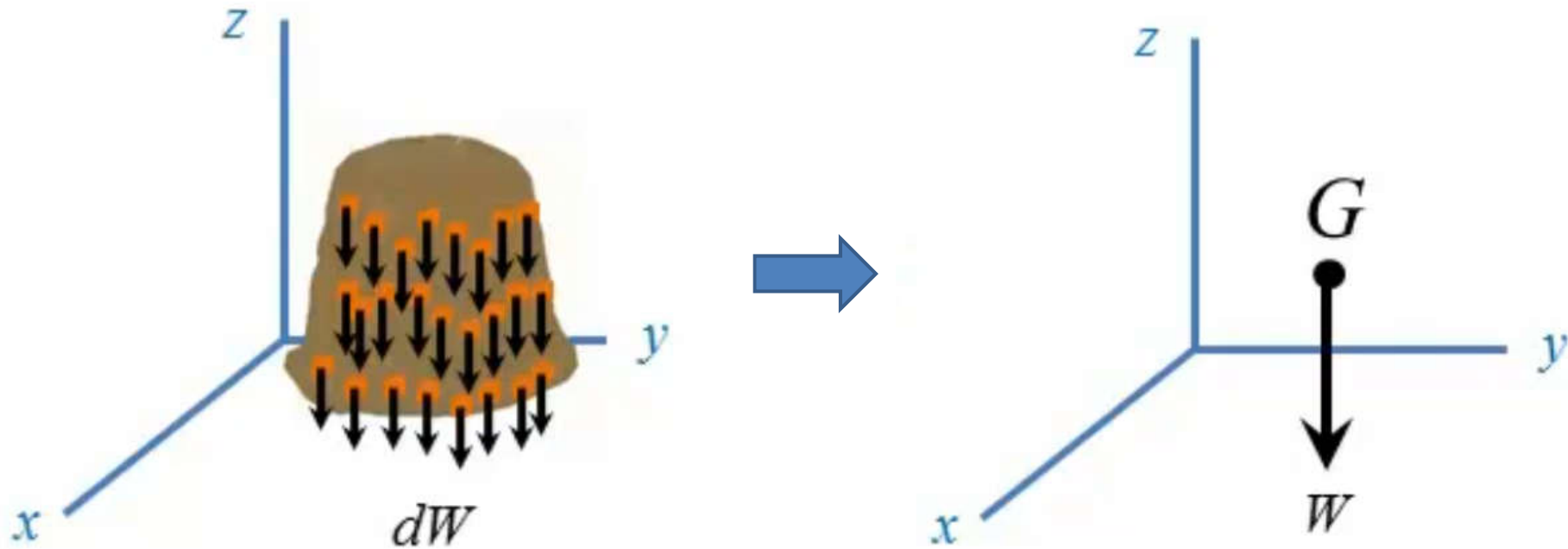


This is **undeformable**  
**rigid** material



$W$  is the total weight  
of this solid

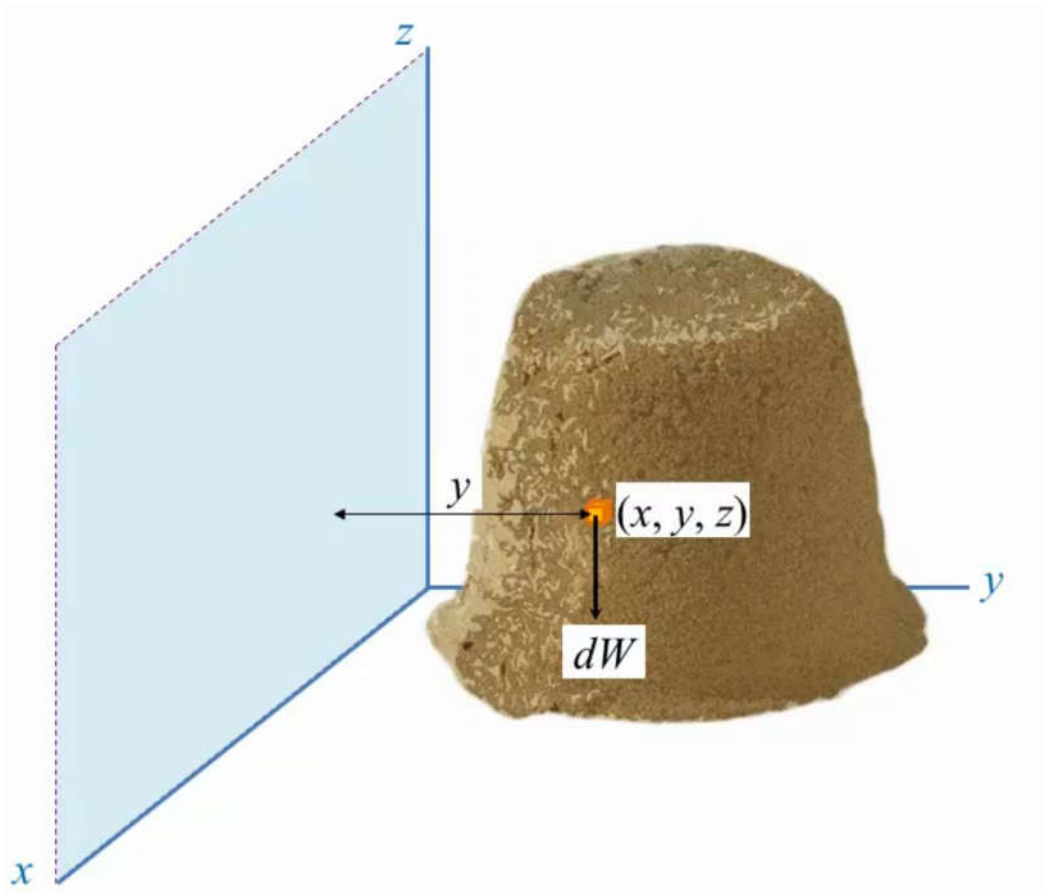
1- We can simplify the analysis by replacing the rigid body by a particle of the same total weight located at this point



**2- For a rigid body, in near-earth gravity, its center of gravity superimposes with its center of mass, and is a unique point fixed in relation to the body.**

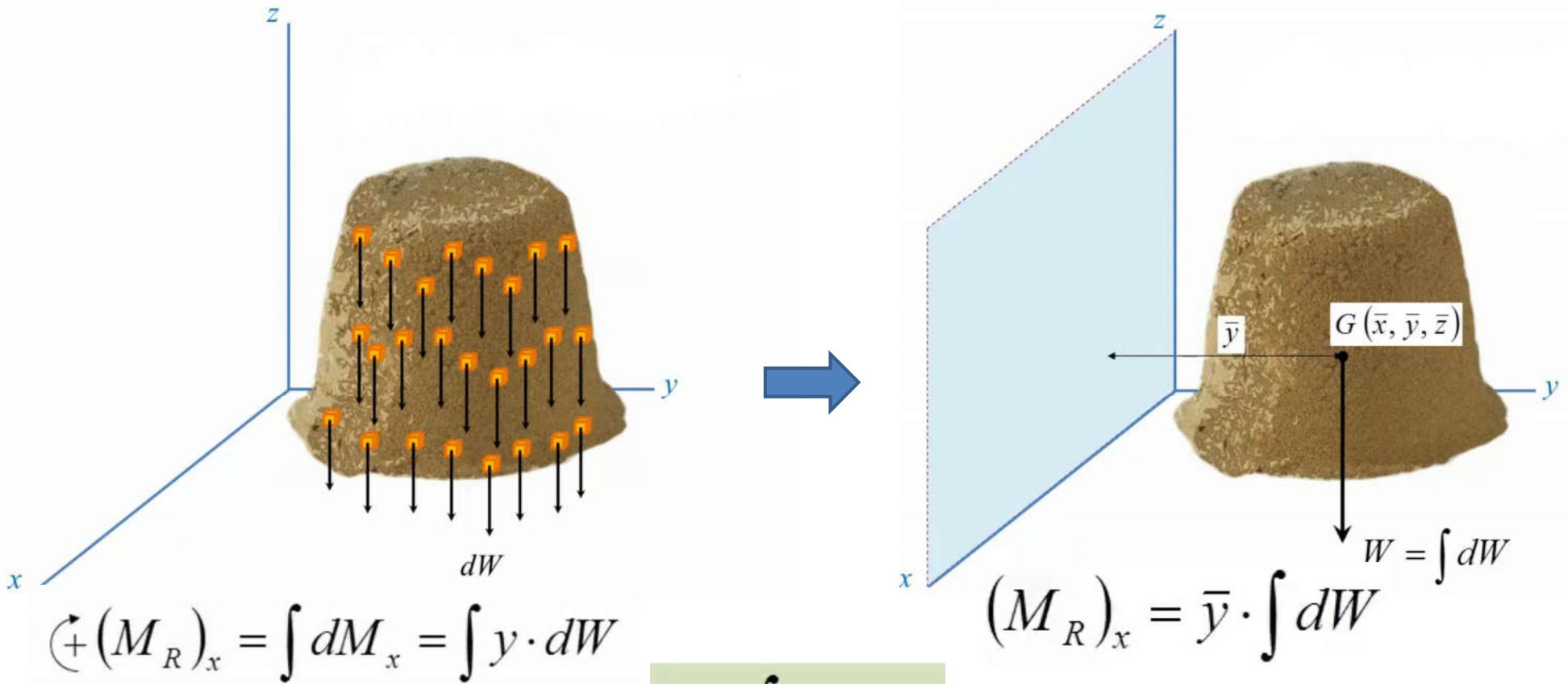
**3- When the body has uniform density, center of gravity and center of mass is also centroid of the volume**

## Engineering Mechanics: Statics



$$\curvearrowright + dM_x = y \cdot dW$$

## Engineering Mechanics: Statics



$$\bar{y} = \frac{\int y \cdot dW}{\int dW}$$



Center of Gravity:

$$\bar{x} = \frac{\int x \cdot dW}{\int dW}$$

$$\bar{y} = \frac{\int y \cdot dW}{\int dW}$$

$$\bar{z} = \frac{\int z \cdot dW}{\int dW}$$



## Engineering Mechanics: Statics

$$W = mg$$

$g$  gravitational acceleration constant , **9.81** m/s<sup>2</sup>

$$\bar{x} = \frac{\int x \cdot dW}{\int dW} = \frac{\int x \cdot dm \cdot g}{\int dm \cdot g} = \frac{\int x \cdot dm}{\int dm}$$

$$\bar{y} = \frac{\int y \cdot dm}{\int dm}$$

$$\bar{z} = \frac{\int z \cdot dm}{\int dm}$$

**Centroid of Mass**

$$\bar{x} = \frac{\int x \cdot dW}{\int dW}$$

$$\bar{y} = \frac{\int y \cdot dW}{\int dW}$$

$$\bar{z} = \frac{\int z \cdot dW}{\int dW}$$

$$m = \rho \cdot V$$

$\rho$  constant density

$$\bar{x} = \frac{\int x \cdot dm}{\int dm} = \frac{\int x \cdot \rho \cdot dV}{\int \rho \cdot dV} = \frac{\int x \cdot dV}{\int dV}$$

$$\bar{x} = \frac{\int x \cdot dV}{\int dV}$$

$$\bar{y} = \frac{\int y \cdot dV}{\int dV}$$

$$\bar{z} = \frac{\int z \cdot dV}{\int dV}$$

$$\bar{z} = \frac{\int z \cdot dm}{\int dm}$$

**Centroid of Volume**

$$V = t \cdot A$$

**$t$  constant thickness**

$$\bar{x} = \frac{\int x \cdot dV}{\int dV} = \frac{\int x \cdot t \cdot dA}{\int t \cdot dA} = \frac{\int x \cdot dA}{\int dA}$$

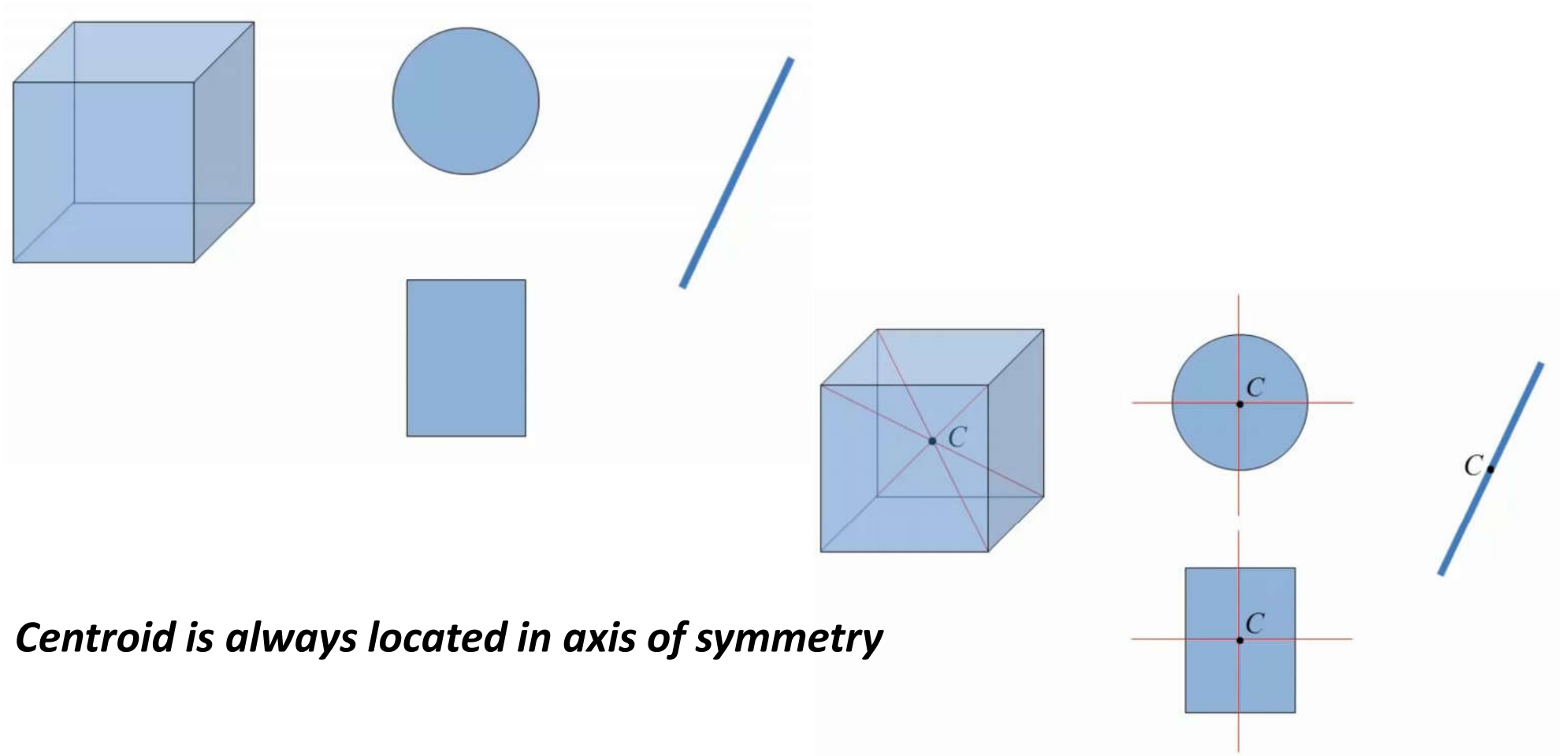
$$\bar{x} = \frac{\int x \cdot dV}{\int dV}$$

$$\bar{x} = \frac{\int x \cdot dA}{\int dA}$$

$$\bar{y} = \frac{\int y \cdot dA}{\int dA}$$

**Centroid of Area**

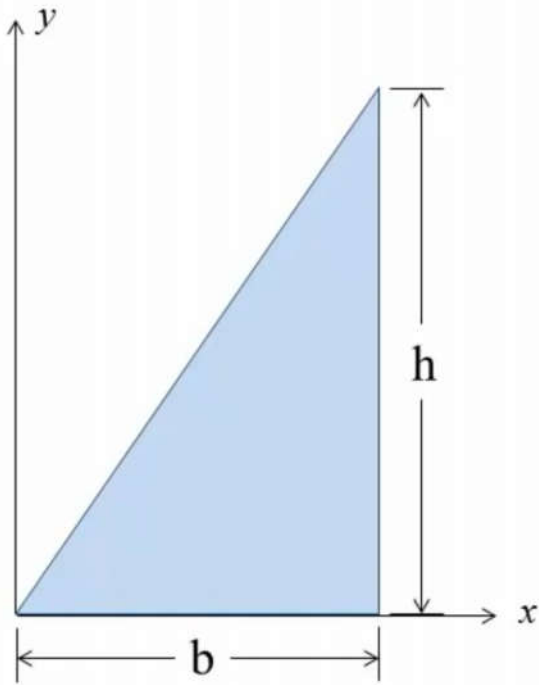
## Engineering Mechanics: Statics



***Centroid is always located in axis of symmetry***

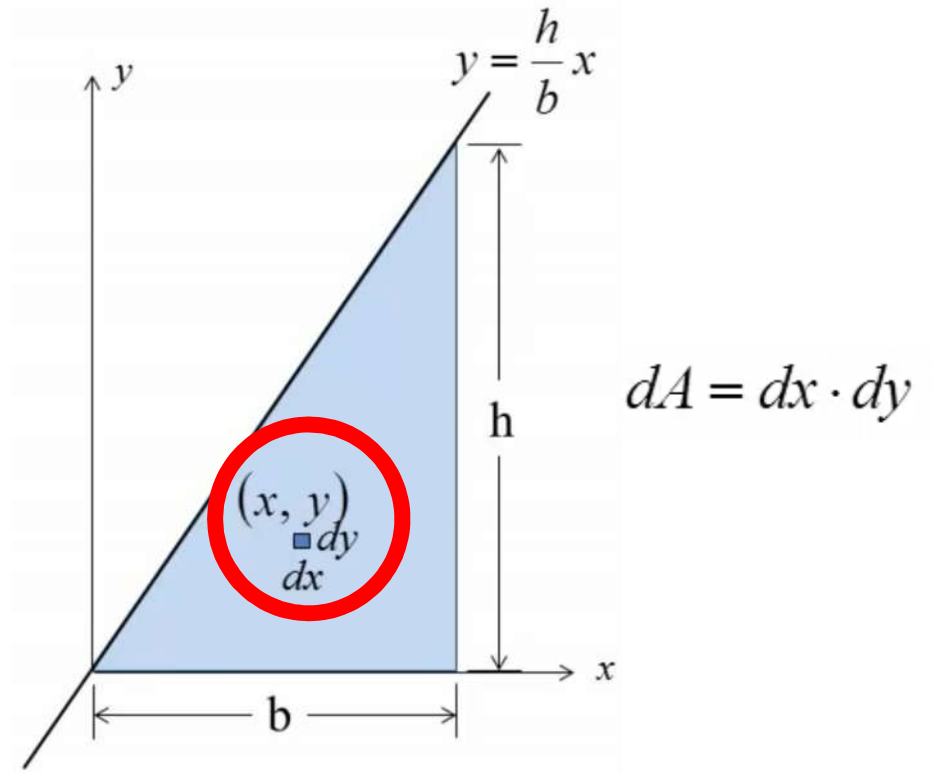
## Engineering Mechanics: Statics

**Example:** find the centroid of this rectangle:



$$\bar{x} = \frac{\int x \cdot dA}{\int dA}$$

$$\bar{y} = \frac{\int y \cdot dA}{\int dA}$$



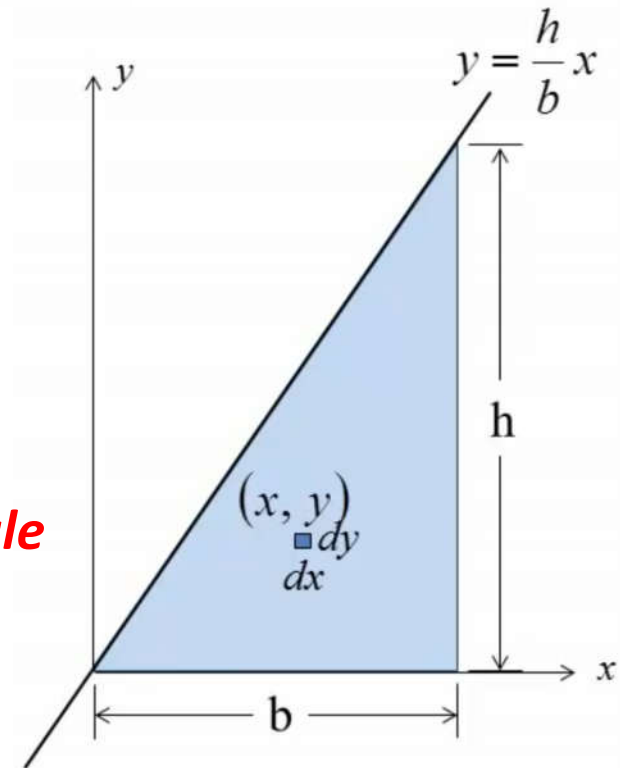
## Engineering Mechanics: Statics

$$\int_A x dA = \int_0^b \int_0^{\frac{h}{b}x} x dy dx = \int_0^b \frac{h}{b} x^2 dx = \frac{h}{b} \cdot \frac{1}{3} x^3 \Big|_0^b = \frac{1}{3} hb^2 \quad dA = dx \cdot dy$$

$$\int_A dA = \int_0^b \int_0^{\frac{h}{b}x} dy dx = \int_0^b \frac{h}{b} x dx = \frac{h}{b} \cdot \frac{1}{2} x^2 \Big|_0^b = \frac{1}{2} hb$$

$$\bar{x} = \frac{\int x \cdot dA}{\int dA} = \frac{2}{3} b$$

**Area of triangle**

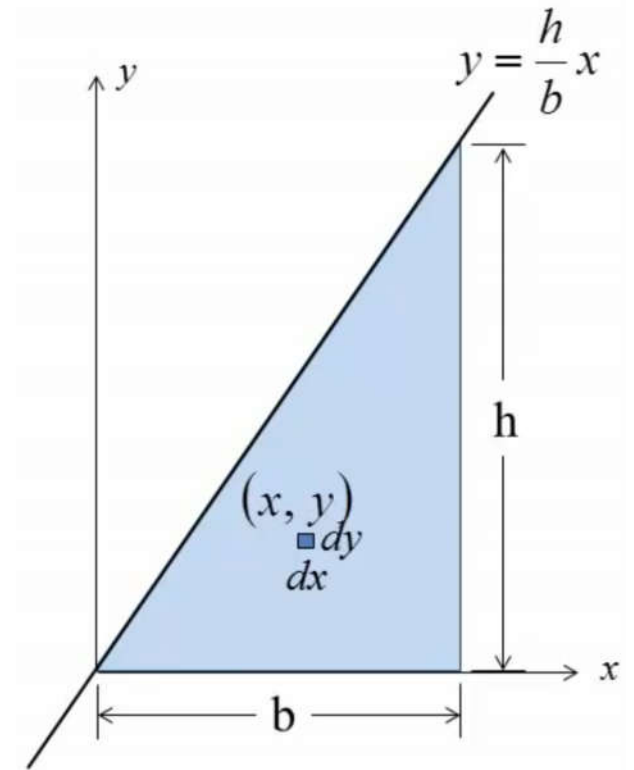


## Engineering Mechanics: Statics

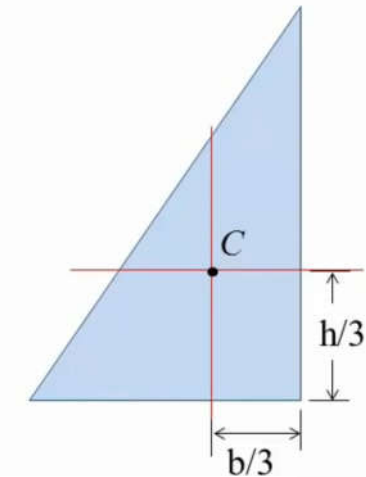
$$\int_A y dA = \int_0^b \int_0^{\frac{h}{b}x} y dy dx = \int_0^b \frac{h^2}{2b^2} x^2 dx$$
$$= \frac{h^2}{b^2} \cdot \frac{1}{6} x^3 \Big|_0^b = \frac{1}{6} h^2 b$$

$$\int_A dA = \frac{1}{2} hb$$

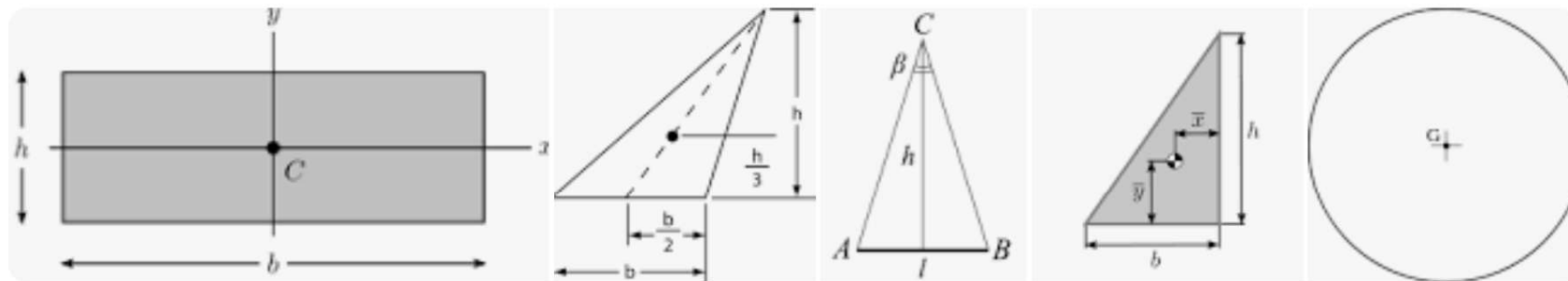
$$\bar{y} = \frac{\int y \cdot dA}{\int dA} = \frac{1}{3} h$$



*The centroid of this rectangle:*



List of centroids - Wikipedia 



The following is a **list of centroids** of various two-dimensional and three-dimensional ... List of centroids.

Article Talk · Language · Watch · Edit. The following is a list of centroids of various two-dimensional an...

[2-D Centroids](#) · [3-D Centroids](#)



## Centroid of composite areas:

$$\bar{x} = \frac{\int \tilde{x} \cdot dA}{\int dA}$$



$$\bar{x} = \frac{\sum \tilde{x} \cdot A}{\sum A}$$

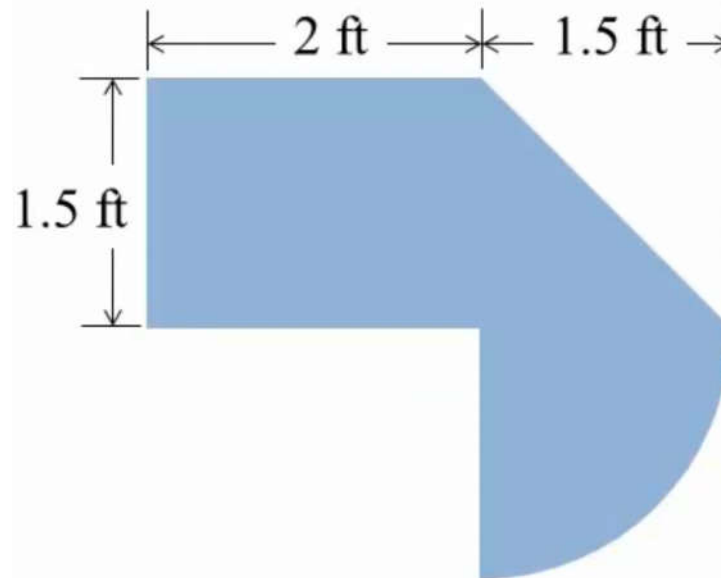
$$\bar{y} = \frac{\int \tilde{y} \cdot dA}{\int dA}$$



$$\bar{y} = \frac{\sum \tilde{y} \cdot A}{\sum A}$$

## Centroid of composite areas:

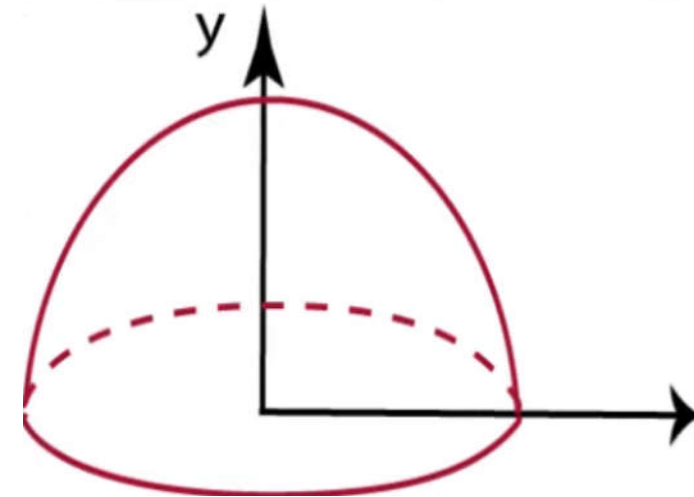
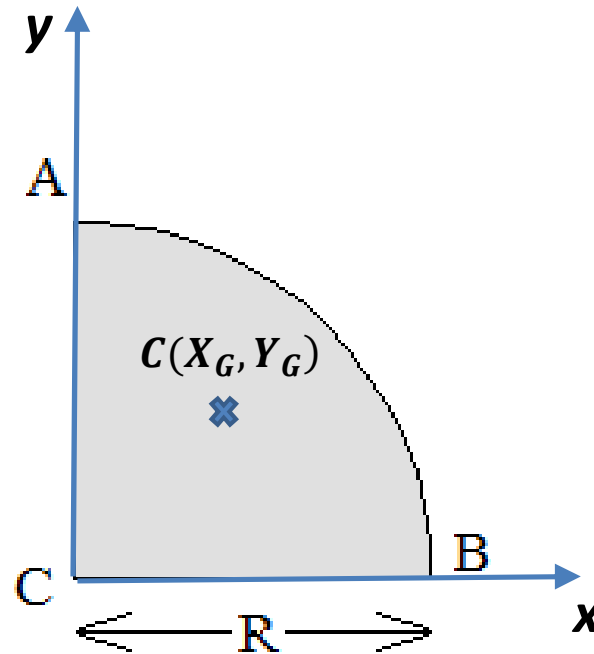
*Example: find the centroid of the area of the composite shape:*



## Centroid of an Area:

Guldin theorem:

$$\left\{ \begin{array}{l} X_G = \frac{V_y}{2\pi S} \\ Y_G = \frac{V_x}{2\pi S} \end{array} \right.$$



$V_y$  Is the **Volume** created by the shape around the X axis

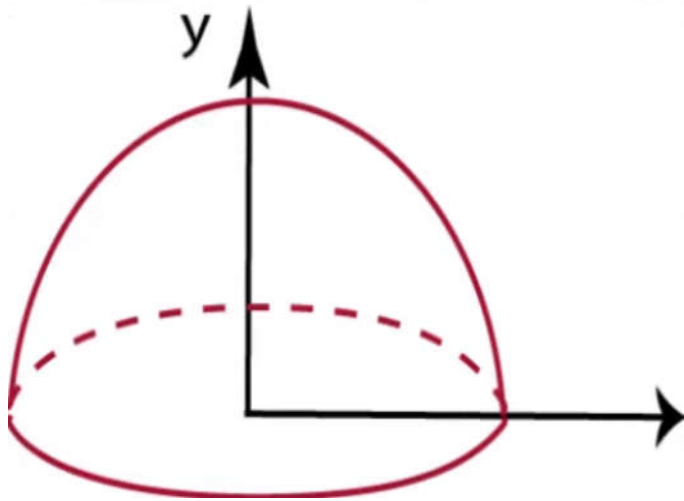
## Centroid of an Area:

Guldin theorem:

$$X_G = \frac{V_y}{2\pi S}$$

$V_y$  = the volume of the half of the sphere

$S$  = the surface of the quarter-circle



$V_y$  Is the Volume created by the shape around the X axis

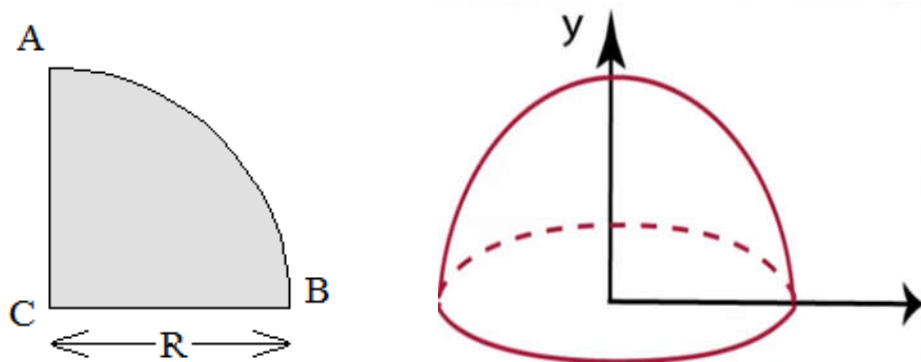
$S$  Is the Initial surface of the shape

## Engineering Mechanics: Statics

$$X_G = \frac{V_y}{2\pi S}$$

$V_y$  = the volume of the half of the sphere

$S$  = the surface of the quart-circle



$$S = \frac{\pi R^2}{4}$$

$$V_y = \frac{2\pi R^3}{3}$$

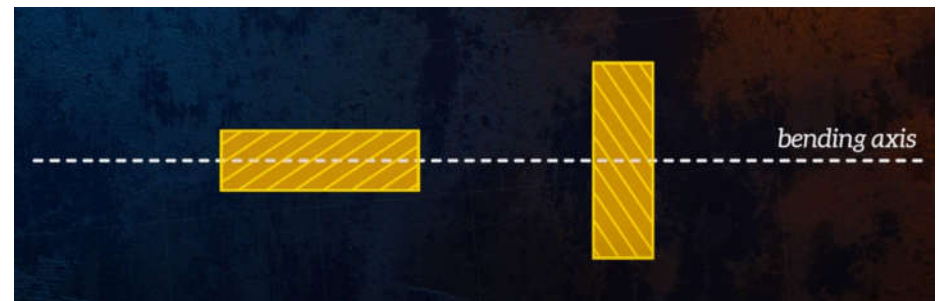
$$X_G = \frac{\frac{2\pi R^3}{3}}{2\pi \frac{\pi R^2}{4}}$$

$$X_G, Y_G = \frac{4R}{3\pi}$$

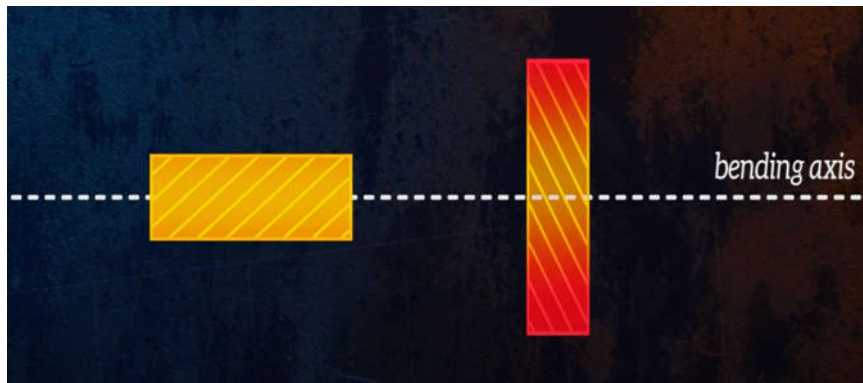
## Moment of inertia

### Objectives:

- You will be able how to find the Moment of inertia of any shape



## Moment of inertia



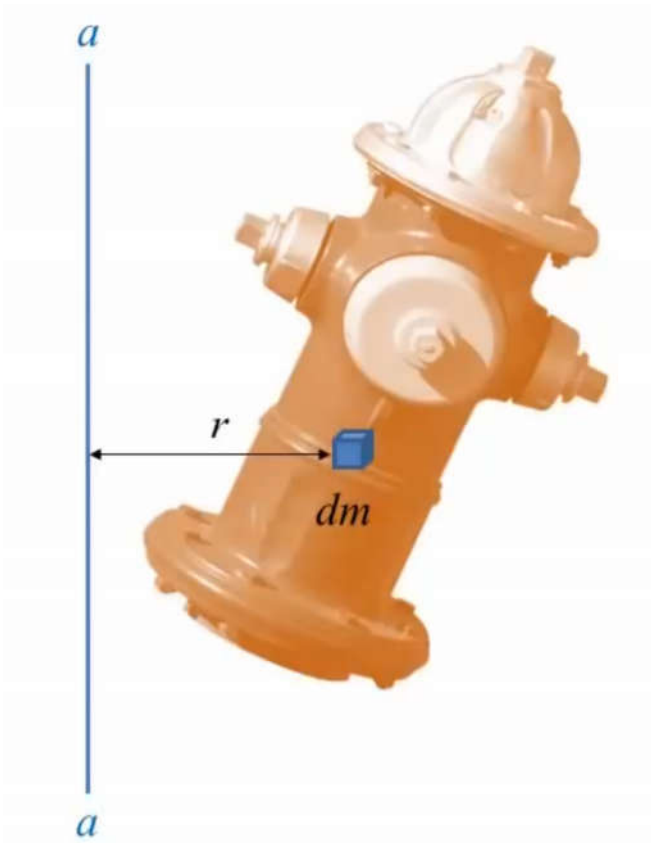
Resistance to bending (rotation) =  
Area moment of inertia (second moment  
of Area)



More material located far from the  
bending axis, it better resists the bending.

Even though, we have the same section of material

## Moment of inertia



$$I_{aa} = \int_m r^2 dm$$

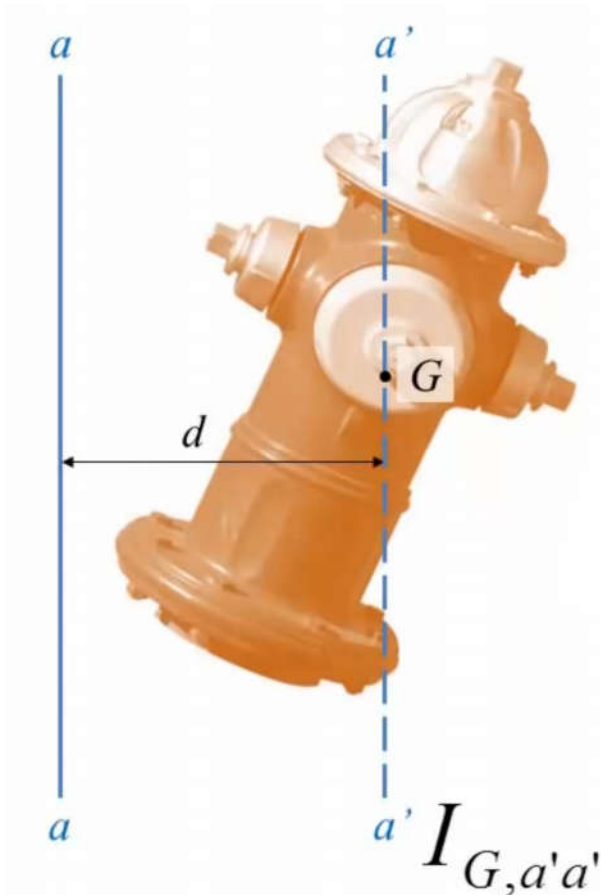
The moment of inertia is relative, different when calculated about different axis

Radius of gyration

$$k_{aa} = \sqrt{\frac{I_{aa}}{m}}$$



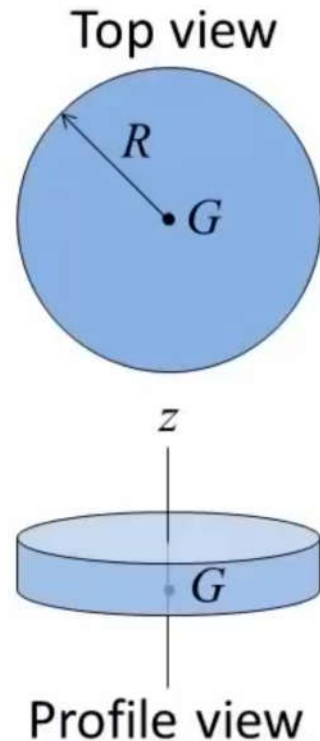
Parallel axis theorem:



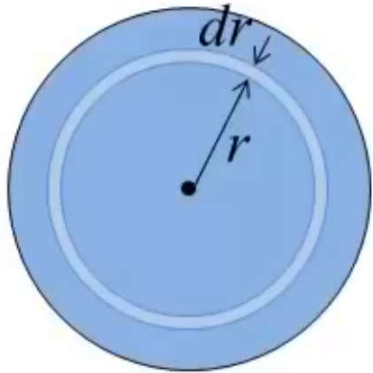
$$I_{aa} = I_{G,aa'} + d^2m$$

### Example:

For a uniform thin disk of mass  $m$ , determine its mass moment of inertia about the  $z$  axis, which passes through its center of gravity  $G$  and is perpendicular to the disk



Solution:



$$dm = \rho dV = \rho \cdot t \cdot dA$$

$$dm = \rho \cdot t \cdot 2\pi r dr$$

$$I_z = \int_m r^2 dm$$

$$I_z = \rho \cdot t \cdot 2\pi \int_m r^3 dm$$

$$I_z = \rho \cdot t \cdot 2\pi \int_m r^3 dm$$

$$I_z = \rho \cdot t \cdot 2\pi t \frac{1}{4} R^4 = \frac{1}{2} \pi \rho t R^4$$

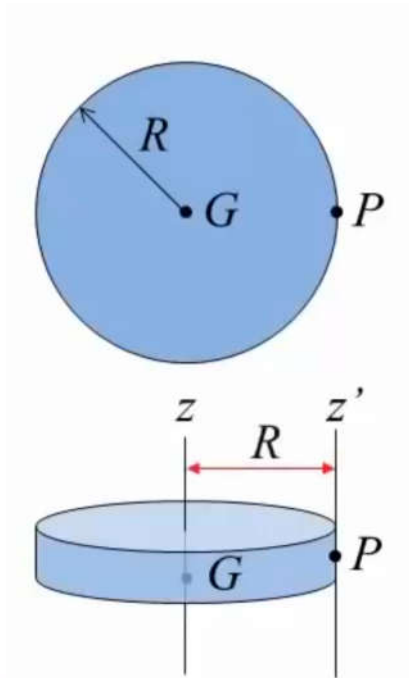
$$V = \pi R^2 t$$

$$m = \rho V = \rho \pi R^2 t$$

$$I_z = \frac{1}{2} m R^2$$

Example 2:

For a uniform thin disk of mass  $m$ , determine its mass moment of inertia about the  $z'$  axis, which passes through point  $P$  and is perpendicular to the disk



We have  $I_z = \frac{1}{2}mR^2$

Parallel axis theorem:

$$I_{z'} = \frac{1}{2}mR^2 + mR^2$$

$$I_{z'} = \frac{3}{2}mR^2$$