

Engineering Mechanics

Brief Introduction and Overview

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Brief Introduction and Overview

- Statics
- Dynamics
- Mechanics of Materials (Deformable Solids)

Prerequisites: Calculus I, University Physics I

Objectives :

- To provide a brief overview of engineering mechanics.
- To introduce the basic sub-disciplines of mechanics.
- To explain the scopes and relations of three common engineering mechanics courses: statics, dynamics and mechanics of materials.

Engineering Mechanics: Statics

Question 1: What is Mechanics?

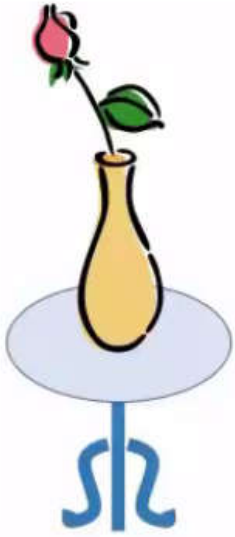
What is *Mechanics*?

1. A branch of **Physics**.
2. **Engineering mechanics** has a focus on the **applications**.
3. Calculates, describes and predicts the effects of **forces** on a **system**.

Engineering Mechanics: Statics

Question 2: What are some examples of what **force** can do?

Engineering Mechanics: Statics



Keep an object **STATIC**



A gravitational Force



Make things **MOVE**

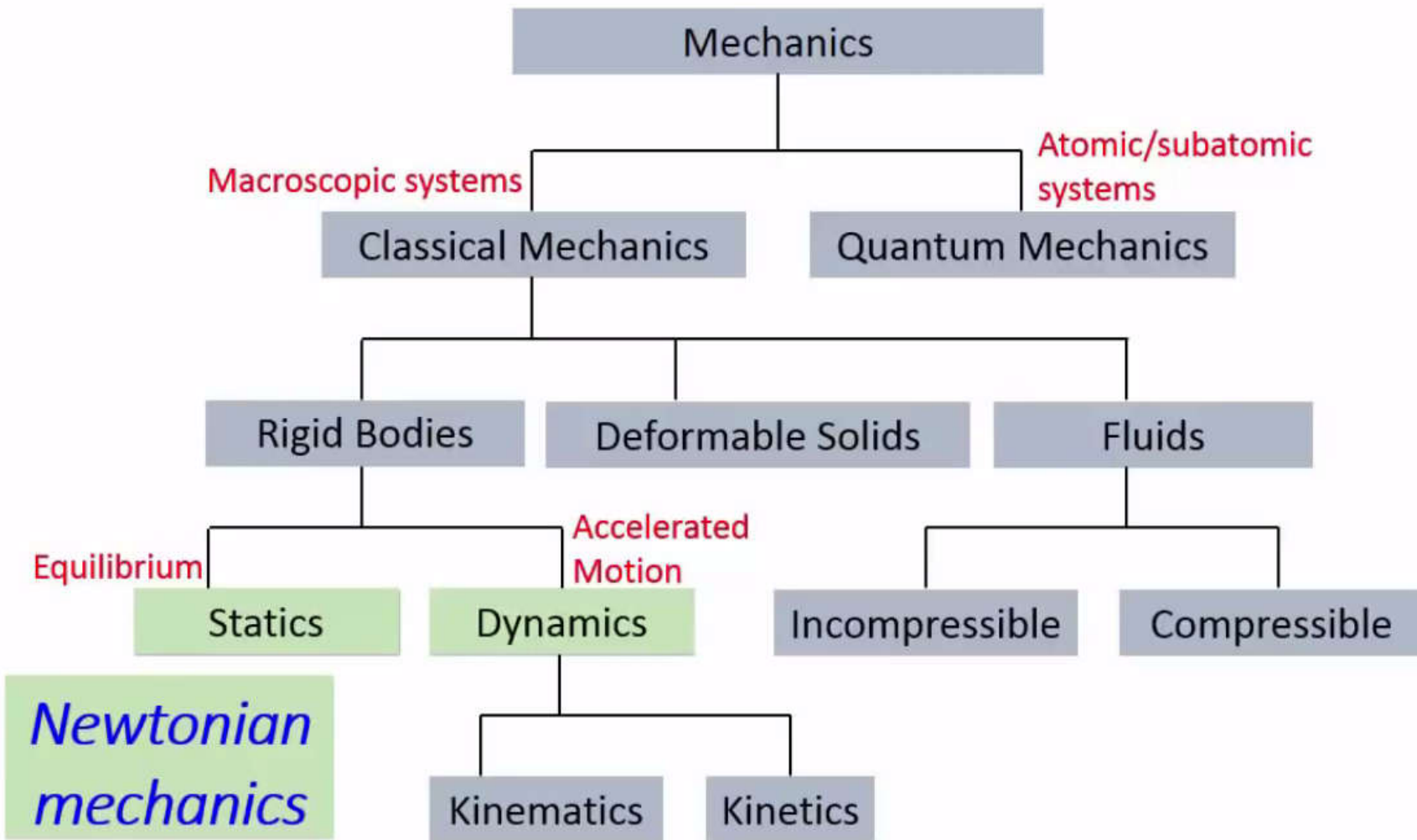


Force can **DEFORM** an object



Make things **ROTATE**

Engineering Mechanics: Statics



Newton's second law



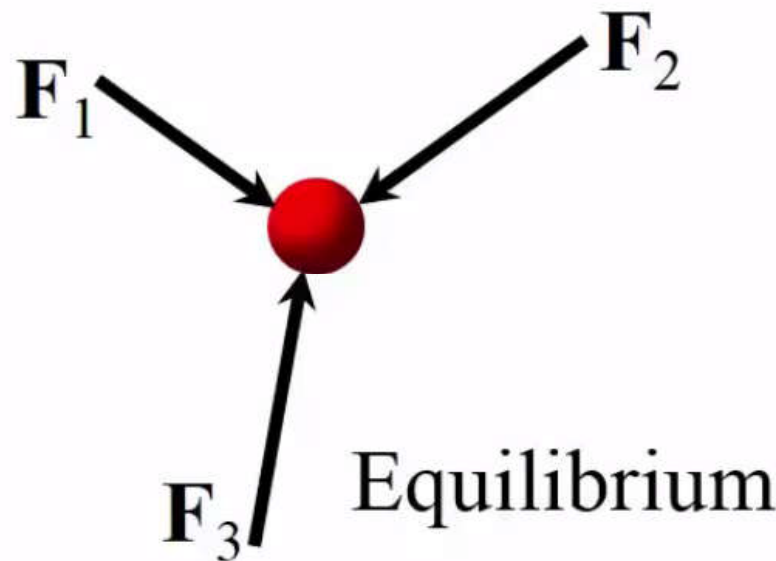
Accelerated motion

$$\mathbf{F} = m\mathbf{a}$$

$$\mathbf{a} = \frac{\mathbf{F}}{m}$$

The acceleration of the movement of an object is *proportional to the resultant force*, and is also in the *same direction* of the resultant force.

Newton's first law

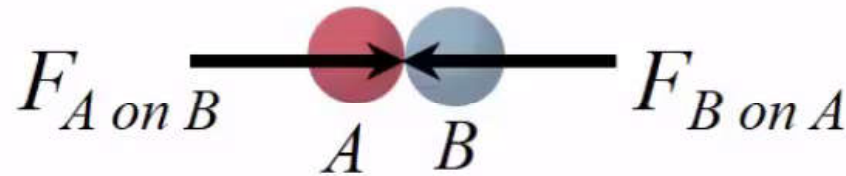


$$\mathbf{F}_R = \mathbf{0}$$

$$\mathbf{a} = \frac{\mathbf{F}_R}{m} = \mathbf{0}$$

An object will remain its original state of motion (*rest* or moving at *constant velocity* in a straight line) if there is no unbalanced force acting on it.

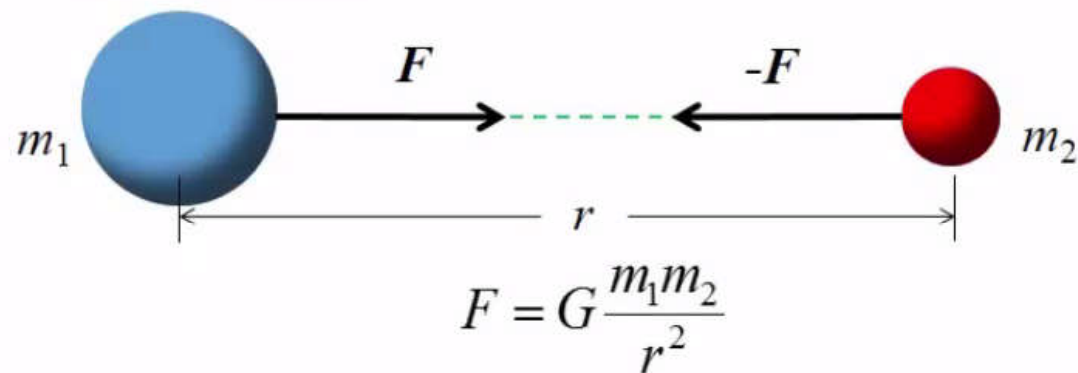
Newton's third law



Action and reaction

The forces of action and reaction between two objects are of the **equal**, **collinear** and **opposite**.

Newton's law of gravitation

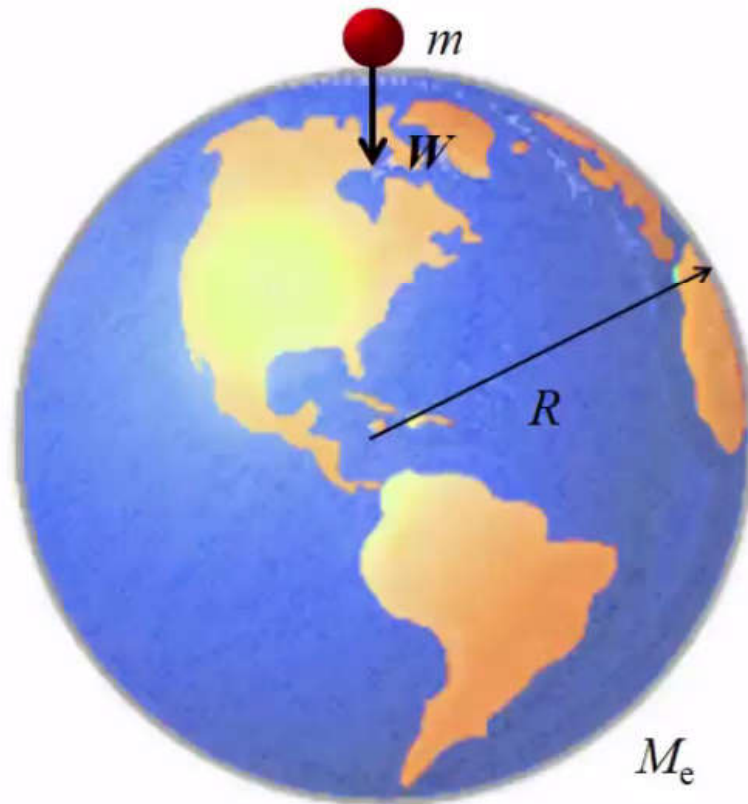


$$F = G \frac{m_1 m_2}{r^2}$$

G : universal constant of gravitation,
 $66.73 \times 10^{-12} \text{ m}^3/(\text{kg} \cdot \text{s}^2)$

The gravitational attraction forces between any two objects are equal and opposite.

Newton's law of gravitation



$$W = G \frac{mM_e}{R^2}$$

R : radius of the earth

M_e : mass of the earth

$$\text{Let } g = G \frac{M_e}{R^2}$$

$$\therefore W = mg$$

g : constant of gravitation of the earth,
9.81 m/s² or 32.2 ft/s².

Engineering Mechanics: Statics

Solid System

Rigid Body
(Particle)

Deformable
Solid

Status

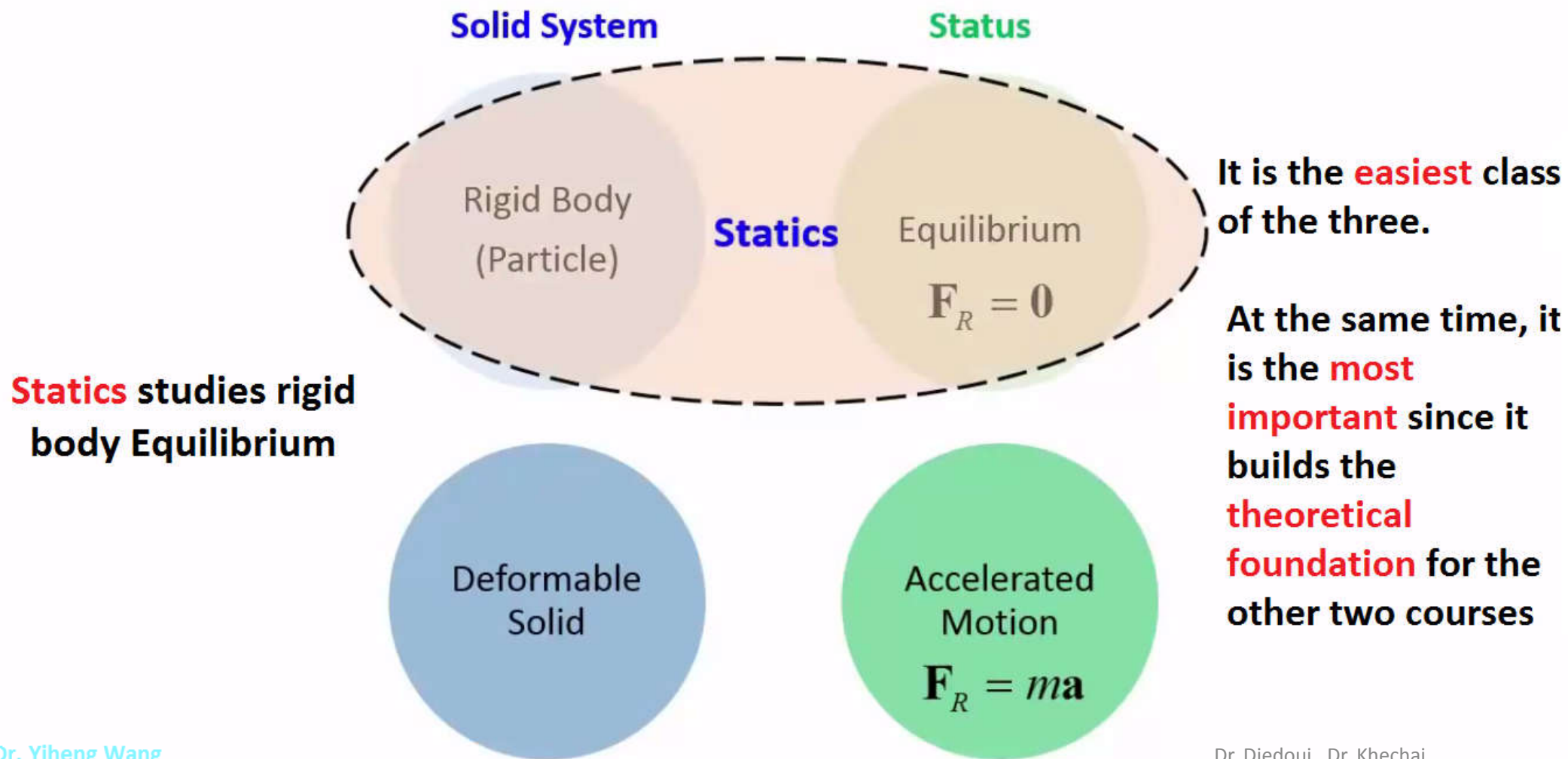
Equilibrium

$$\mathbf{F}_R = \mathbf{0}$$

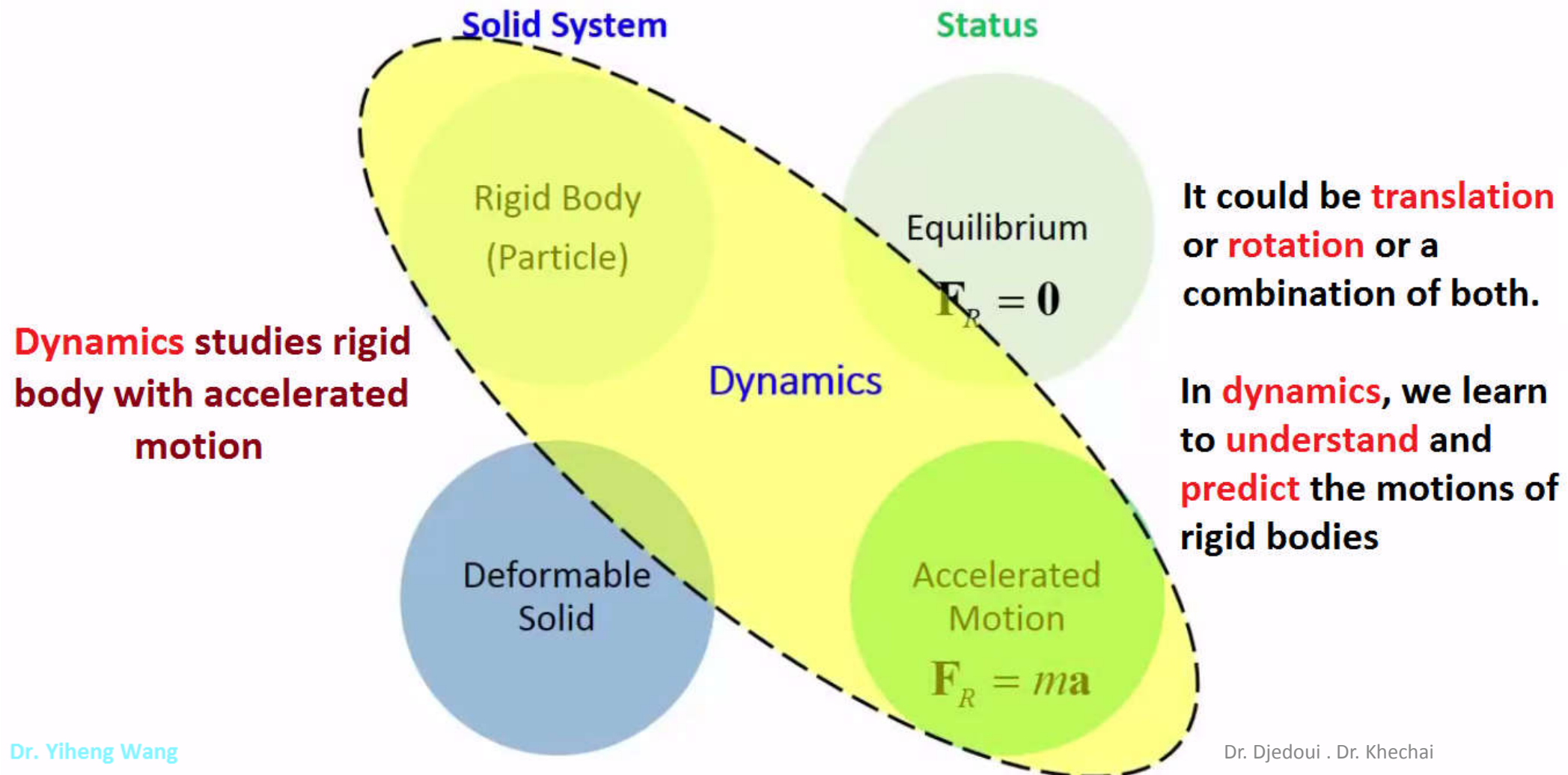
Accelerated
Motion

$$\mathbf{F}_R = m\mathbf{a}$$

Engineering Mechanics: Statics



Engineering Mechanics: Statics



Engineering Mechanics: Statics

Solid System

Status

Rigid Body
(Particle)

Equilibrium

$$\mathbf{F}_R = \mathbf{0}$$

Mechanics of
Materials

Deformable
Solid

Accelerated
Motion

$$\mathbf{F}_R = m\mathbf{a}$$

Mechanics of materials
studies deformable
solids in equilibrium

We want to know
how forces cause
stress, deformation
and even **failure** in
the system.

It is important in
many fields such as
construction or
design.

Fundamental Concepts:

Basic quantities and idealization

Objectives :

- To introduce the **basic quantities** of mechanics.
- To introduce the concept of **idealization** commonly used in mechanics.

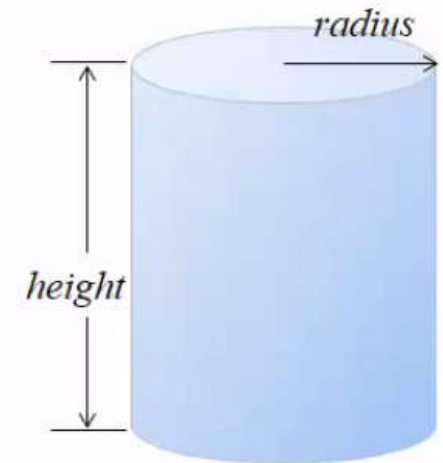
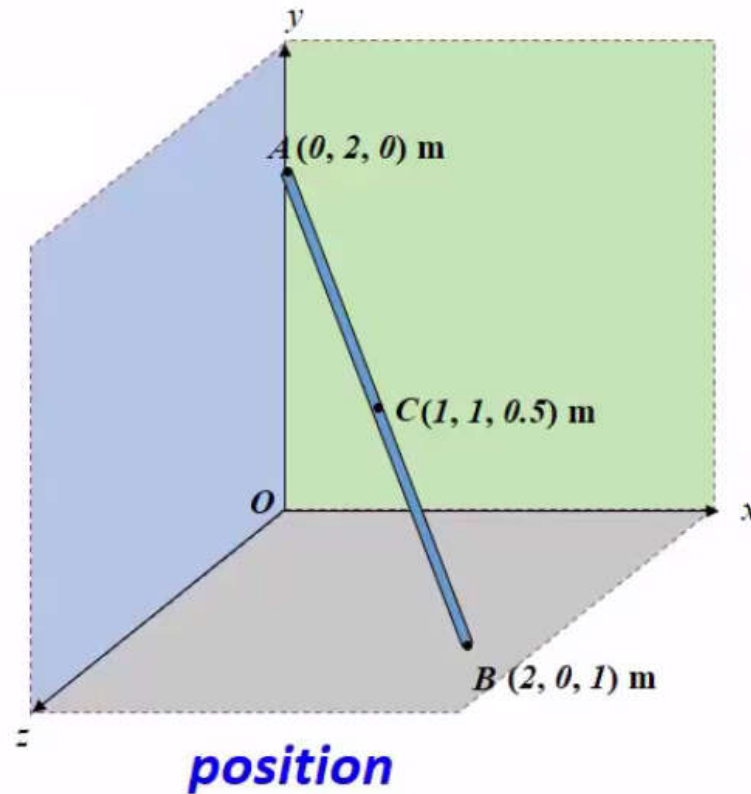
Basic quantities
length time mass force

Engineering Mechanics: Statics

Question 1: In your own words, explain what *length*, *time*, *mass* and *force* are respectively.

Length

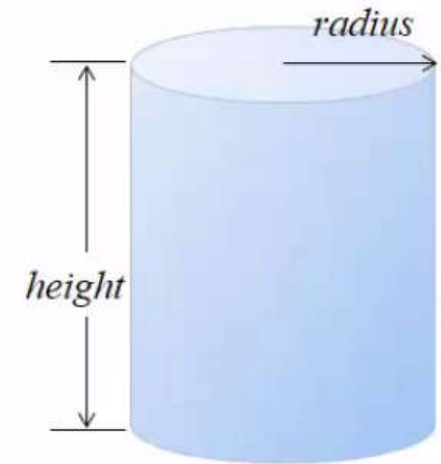
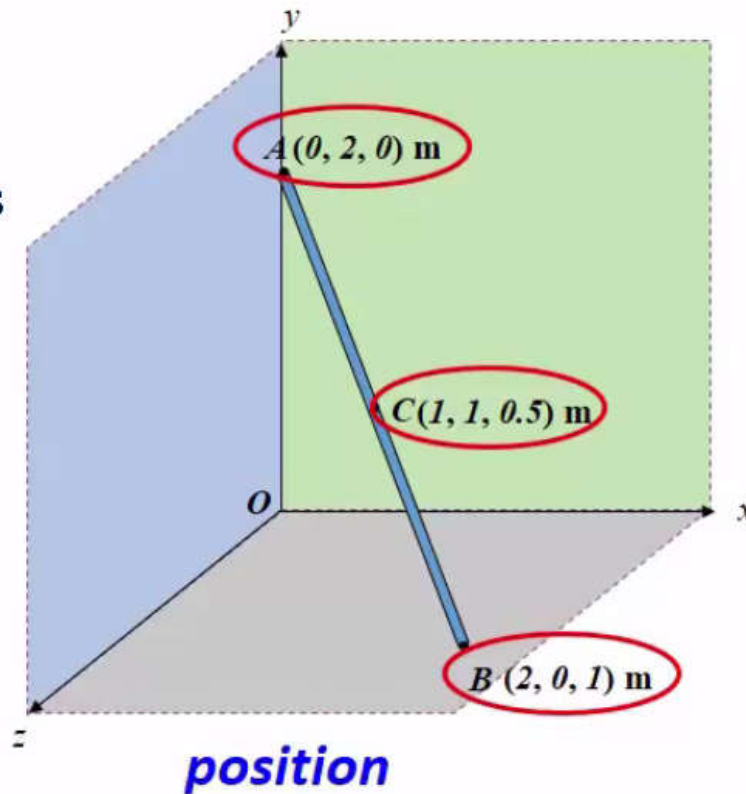
can be used to describe the **position** in space, the **size** of a physical system, and the **geometric properties** of a body.



size,
geometric properties

Length

Coordinates are the 3 lengths measured from the **origin** along **x**, **y** and **z** direction respectively in an established **rectangular coordinate system**.



**size,
geometric properties**

Unit: [m] or [ft]

Time



describes the **succession** of events.

Example: **Speed** describes the **position** of an object with respect to **time**.

Time is a very important concept in the subject of **Dynamics**, but in **Statics**, we mainly deal with objects that are **motionless**.

Unit: [s]

statics : time-independent
dynamics: time-dependent

Engineering Mechanics: Statics

Question 2: A person who weighs 143 pounds is about 65 kilograms, correct? Is *weight* the same as *mass*?

Mass

is a measure of **quantity** of matters.

Mass is a physical property that characterizes the extent of **force** and object experiences in a **gravitational field**.

Mass characterizes also the **resistance** of an object to changes in its state of motion.

Mass is **NOT** the same as **weight** since **weight** is a **force**

$$F = G \frac{m_1 m_2}{r^2}$$

$$\mathbf{a} = \frac{\mathbf{F}}{m}$$



Unit: [kg] or [slug]

Dr. Djedoui . Dr. Khechai

Force

The concept of **force** characterizes the **action** and **reaction** between two bodies.

They could be **CONTACT** between the two bodies.

There could be **NO CONTACT**.

Force is a **vector** and it is fully described by:

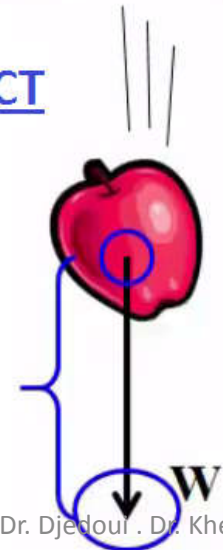
- magnitude*
- direction*
- point of application*

Unit: [N] or [lb]

CONTACT



NO CONTACT



Dr. Djedoui . Dr. Khechai

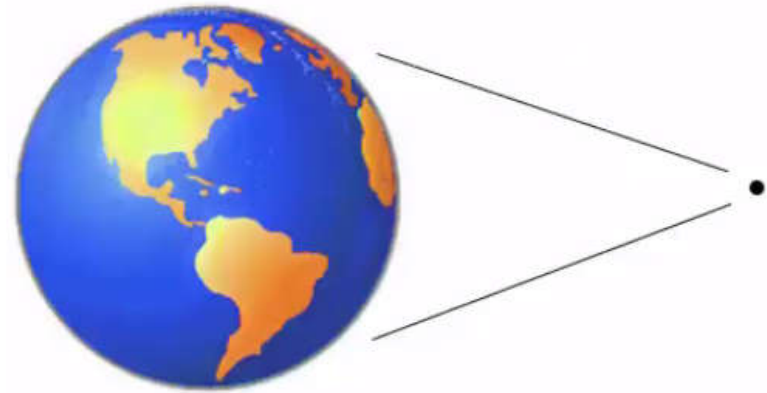
Idealizations

means to use **scientific models** to represent phenomena, so that they can be **simplified** to an extent.

particle

An object can be modeled as a **particle** when its geometry and dimension are **negligible** for the interest of the study

A particle is considered to only occupy a single point in space with **NO** shape or size and it has **NO** properties except its **MASS**.



rigid body

not only has mass but also has **dimensions** and **geometry**.

In other words, it has **size** and **shape** that need to be taken into consideration in our analysis.

Unlike real world objects a rigid body does **NOT** have any other material properties **such as ELASTICITY**, therefore it will **not deform**.



concentrated force

assumes that a force only acts on a **point**, although in reality, forces are applied to an **AREA** or a **VOLUME**.

Example:

The **weight** of an object is distributed throughout its body, but in our analysis, we often use a **concentrated force** that is placed at the **CENTER of GRAVITY** in the object to replace the distributed gravitational force.

